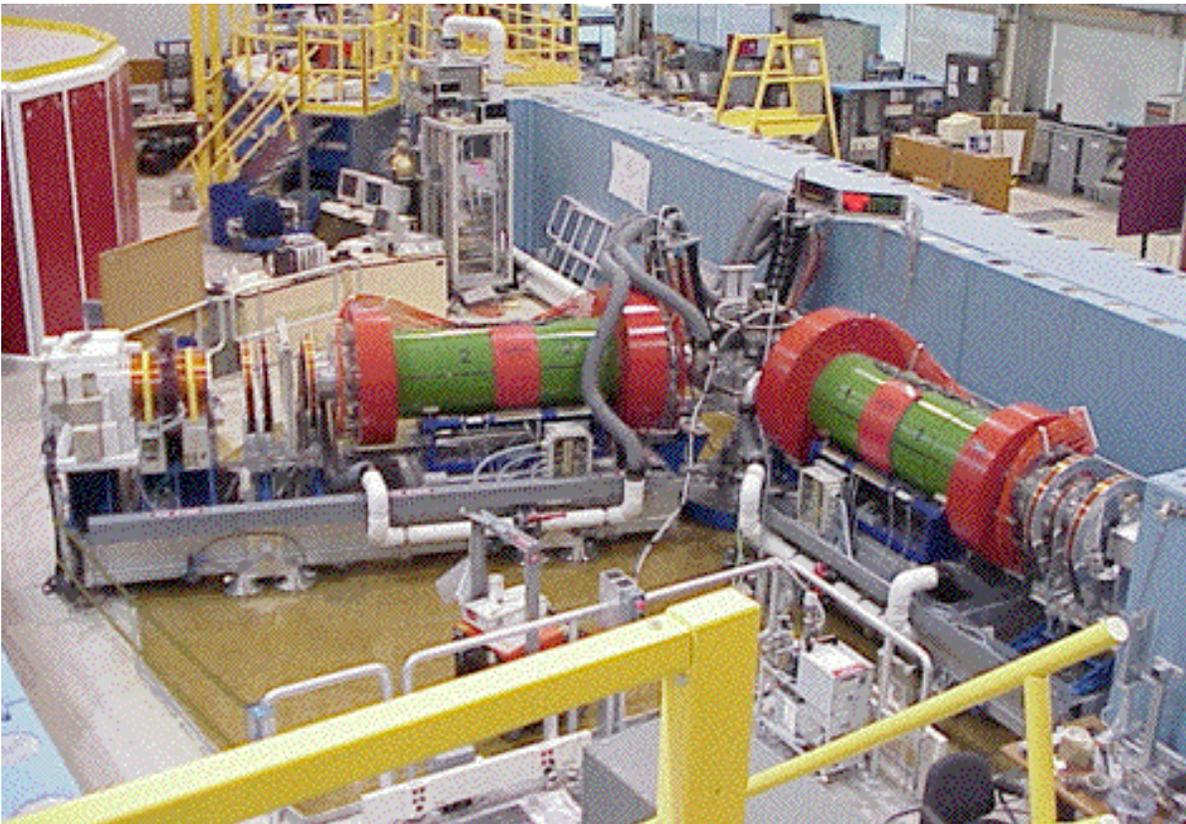


Neutron Spin Echo Spectroscopy (NSE)

A. Faraone, D.P. Bossev, S.R. Kline, L. Kneller

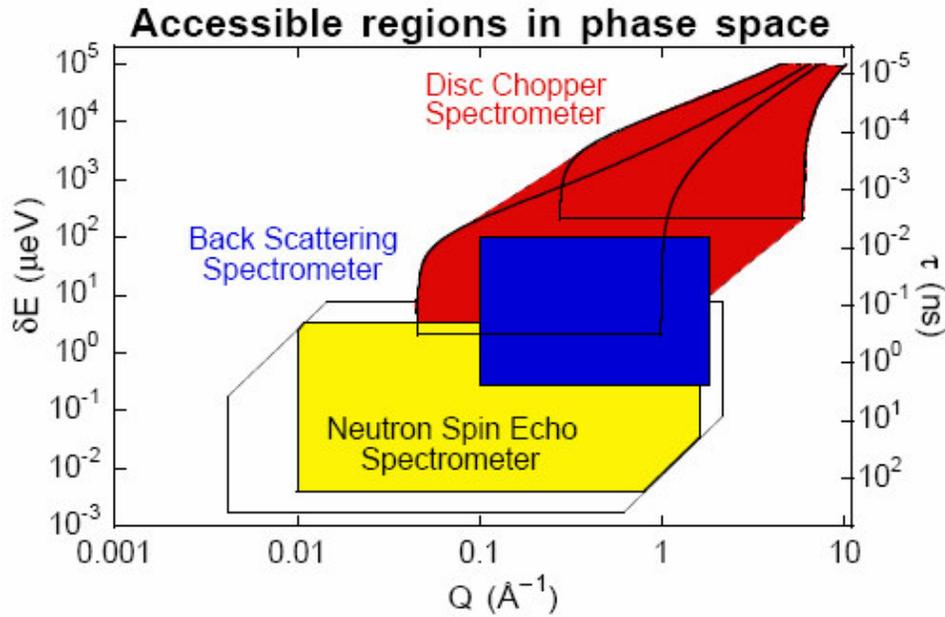


*NCNR, NIST
Gaithersburg, MD 20899*

E-mail:
afaraone@nist.gov

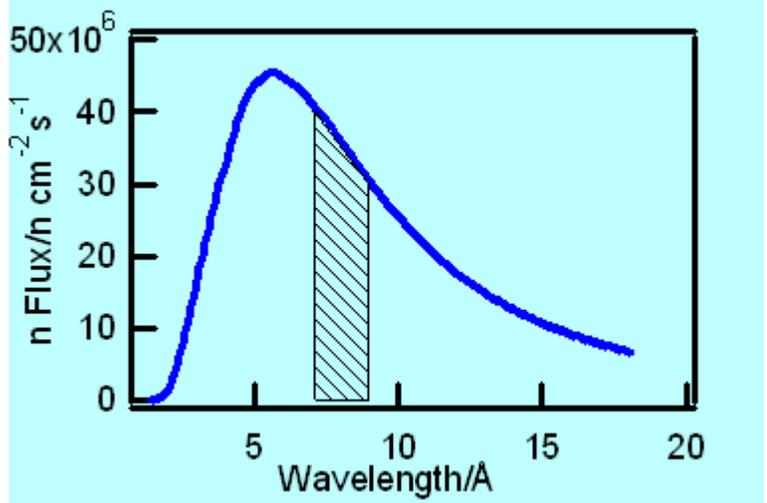
Internet:
<http://www.ncnr.nist.gov/>

Why we need a magnetic field?



- **Goal:** $\delta E = 10^{-5} - 10^{-2}$ meV (very small!!!)
- We need low energy neutrons. Cold neutrons: $\lambda = 5 - 12 \text{ \AA}$, $E = 0.5 - 3.3$ meV.
- A “classical” inelastic technique works in two steps: preparation of the incoming monochromatic beam and analysis of the scattered beam.

- In Neutron spin echo the precessing neutron spin is employed as a kind of “individual” clock for each neutron. Thus, the velocity (energy) change of the neutrons can be measured directly in a single step.
- NSE technique allows the use of neutron beam wavelength spread $\Delta\lambda/\lambda = 5 - 20\%$, and therefore reasonably intense.



Neutron Flux along NG5 guide to NSE

Neutrons in magnetic fields: Precession

Mass, $m_n = 1.675 \times 10^{-27}$ kg

Spin, $S = 1/2$ [in units of $h/(2\pi)$]

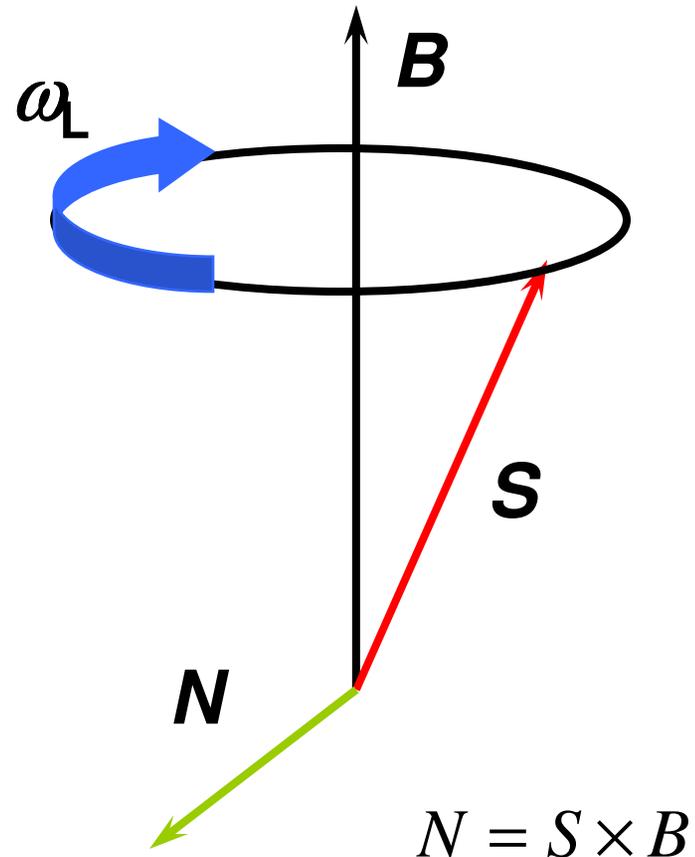
Gyromagnetic ratio $\gamma = \mu_n/[S \times h/(2\pi)] =$
 $1.832 \times 10^8 \text{ s}^{-1} \text{ T}^{-1}$ (29.164 MHz T⁻¹)

- The neutron will experience a torque from a magnetic field B perpendicular to its spin direction.

- Precession with the Larmor frequency:

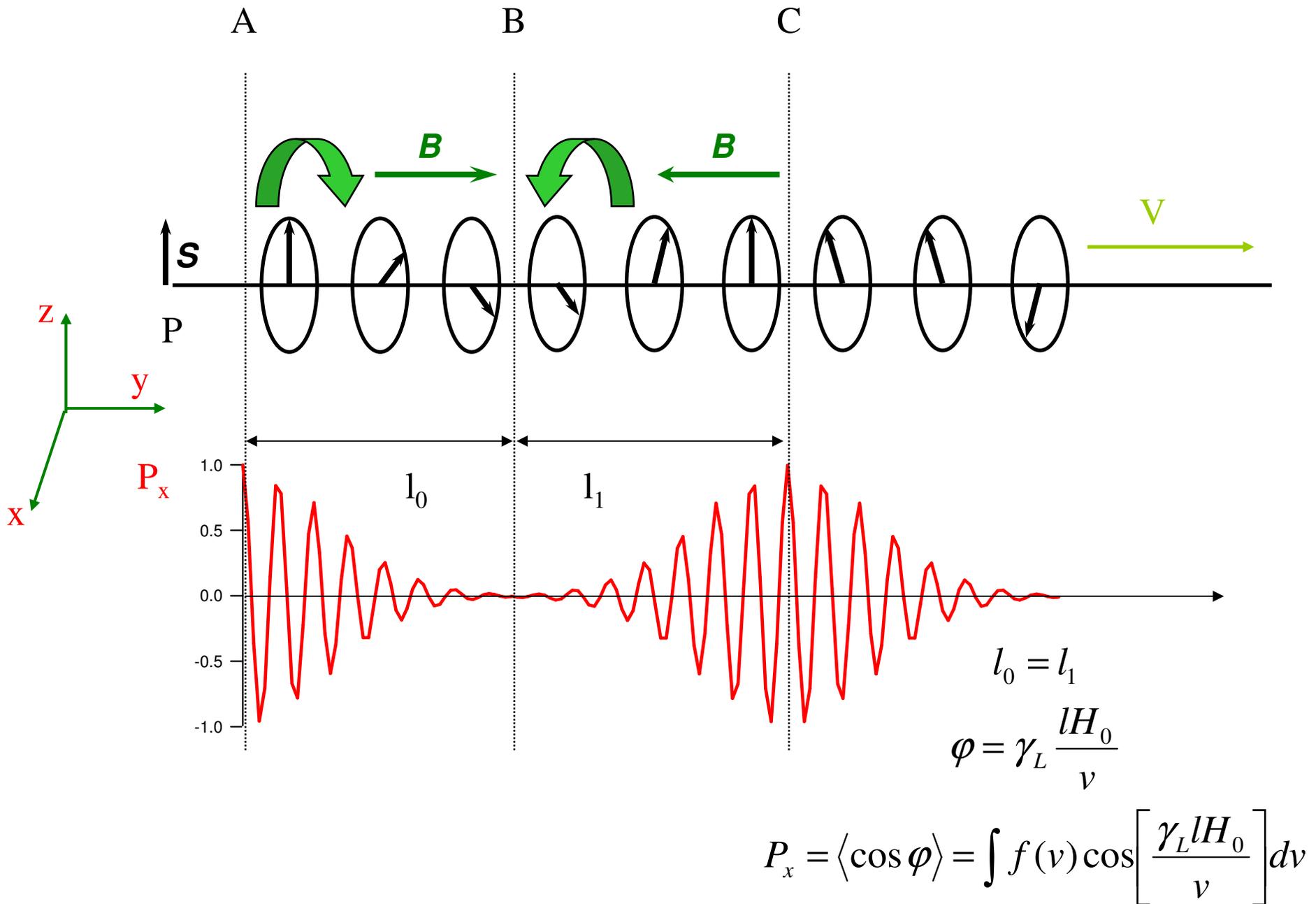
$$\omega_L = \gamma B$$

- The precession rate is predetermined by the strength of the field only.



$$\frac{dS}{dt} = \gamma S \times B = S \times \omega_L$$

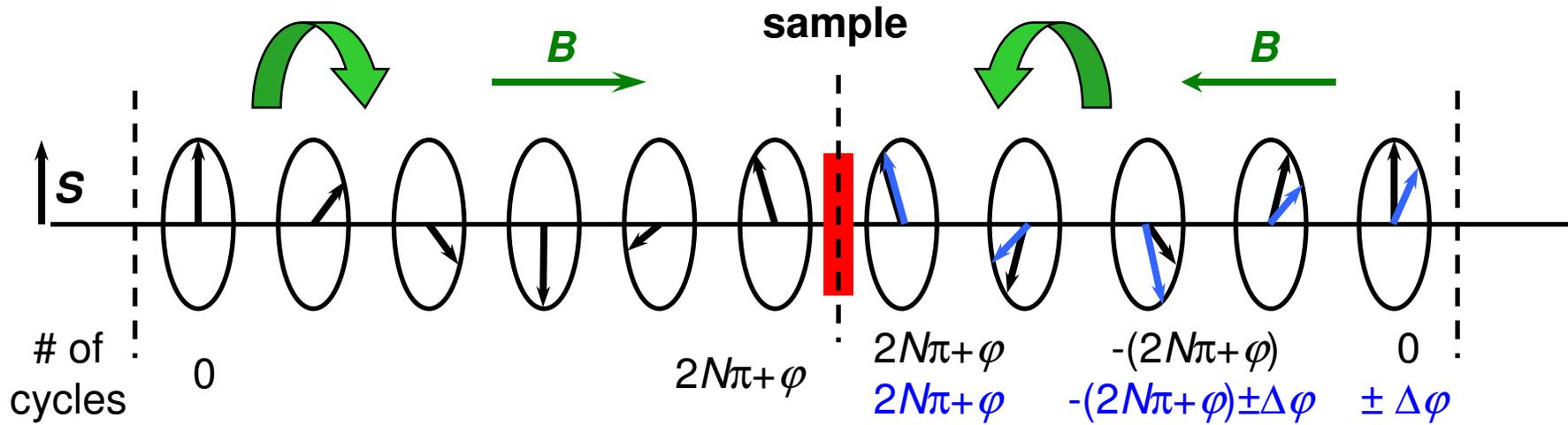
Spin echo effect



Monochromatic beam

• elastic scattering

• inelastic scattering



$$\phi = \gamma B \frac{L}{v}$$

$$\Delta\phi = \gamma B L \left(\frac{1}{v} - \frac{1}{v'} \right) = \frac{\gamma B L \Delta v}{v^2}$$

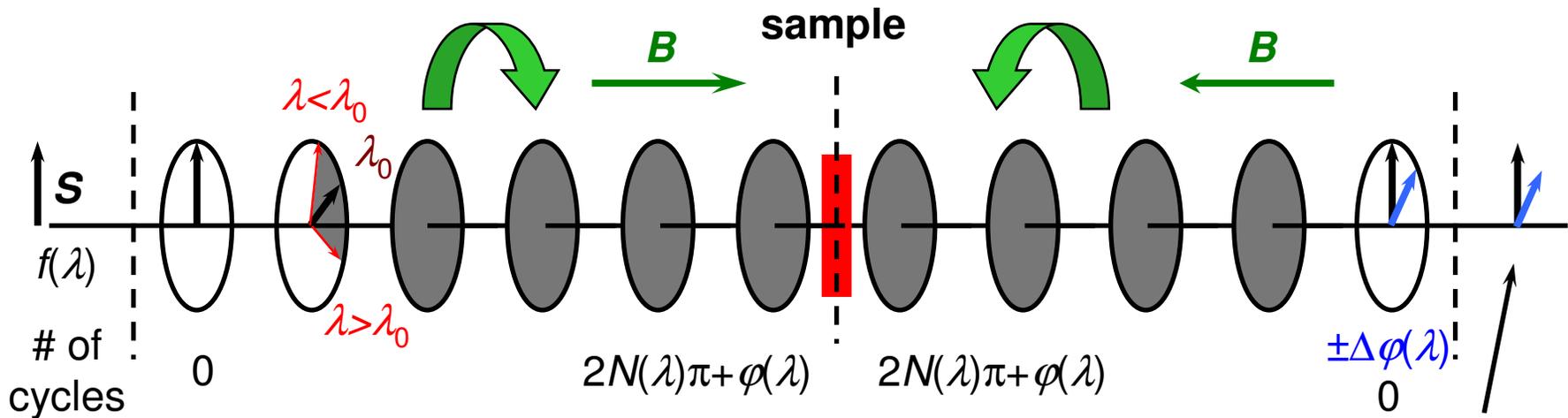
$$N(\lambda) = \frac{1}{2\pi} \int \frac{4\pi\gamma\mu_N B m \lambda}{h^2} dl = \frac{2\gamma\mu_N m \lambda}{h^2} \int B dl = 7370 \times J [T \cdot m] \times \lambda [\text{\AA}]$$

$$J = \int B dl$$

J field integral. At NCNR: $J_{\max} = 0.5 \text{ T}\cdot\text{m}$
 $N(\lambda=8\text{\AA}) \sim 3 \times 10^5$

$$\frac{\Delta v}{v} \approx \frac{1}{N} \approx 10^{-5} !$$

Polychromatic beam



$$N_0 \equiv N(\lambda_0); \text{ then } N(\lambda) = N_0 \frac{\lambda}{\lambda_0}$$

The measured quantity is the spin component along z: $\cos(\Delta\varphi(\lambda))$:

$$\Delta\varphi(\lambda) = N_0 \frac{\delta\lambda}{\lambda_0} + \Delta N_0 \frac{\lambda}{\lambda_0} + \Delta N_0 \frac{\delta\lambda}{\lambda_0}$$

Energy change

Asymmetry between coil field integrals

Neglect 2nd order terms for small asymmetries or quasielastic scattering

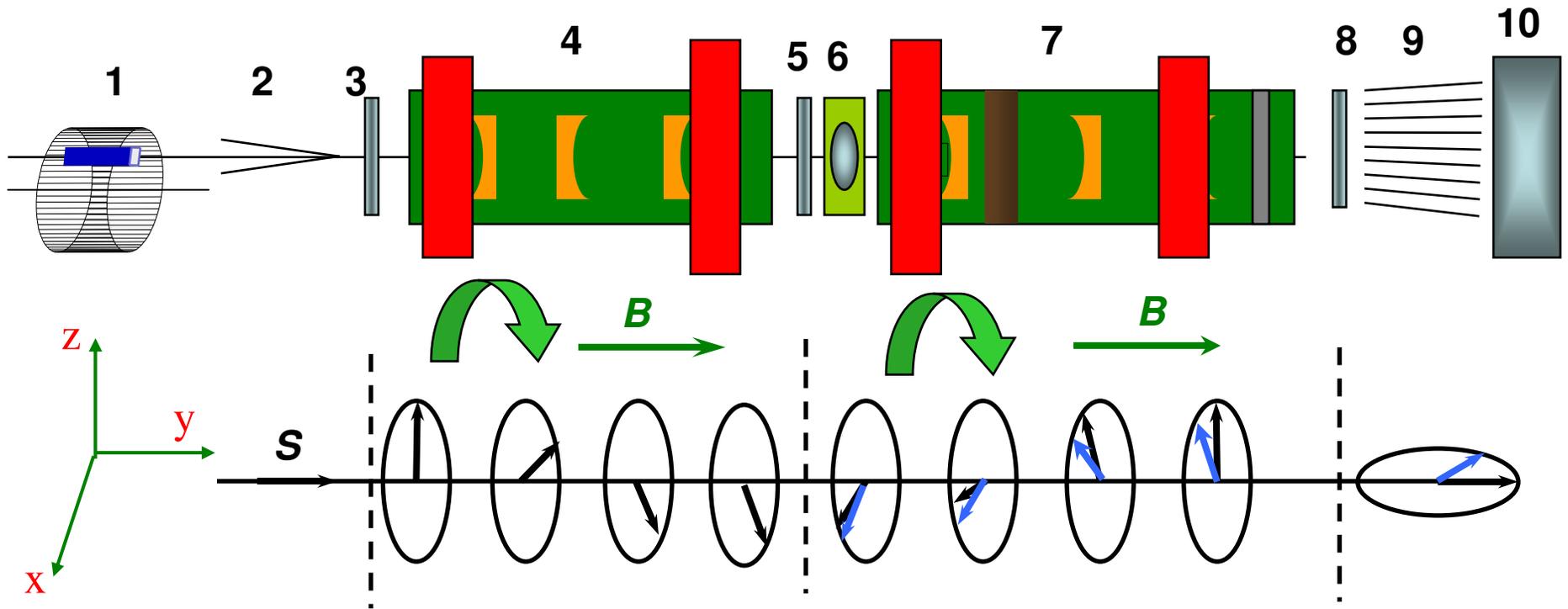
$$\begin{aligned} \cos[2\pi(N_0\delta\lambda + \Delta N_0\lambda)/\lambda_0] &= \\ &= \cos\left(2\pi N_0 \frac{\delta\lambda}{\lambda_0}\right) \cos\left(2\pi \Delta N_0 \frac{\lambda}{\lambda_0}\right) + 2\text{nd order terms} \end{aligned}$$

Neglected

The Principles of NSE

- If a spin rotates anticlockwise & then clockwise by the same amount it comes back to the same orientation
 - Need to reverse the direction of the applied field
 - Independent of neutron speed provided the speed is constant
- The same effect can be obtained by reversing the precession angle at the mid-point and continuing the precession in the same sense
 - Use a π rotation
- If the neutron's velocity is changed by the sample, its spin will not come back to the same orientation
 - The difference will be a measure of the change in the neutron's speed or energy.

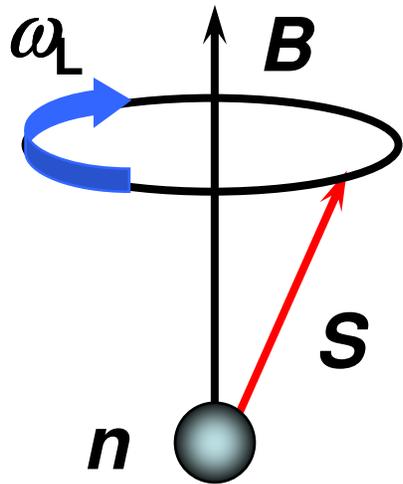
NSE Spectrometer schematic



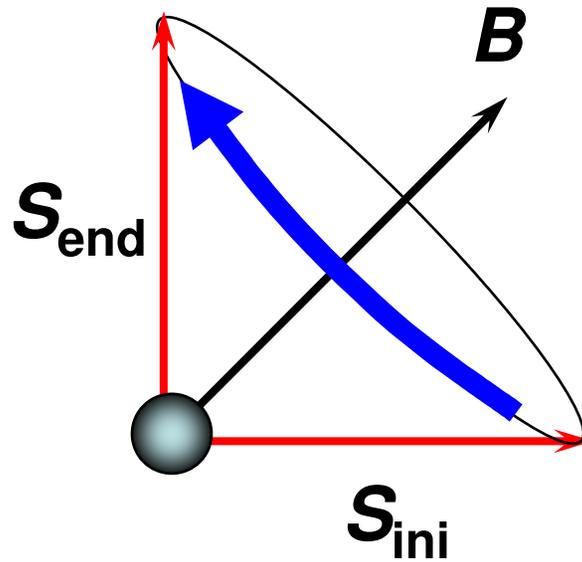
1. Velocity selector (selects neutron with certain λ_0)	5. π flipper (Provides phase inversion)	9. Polarization analyzer (radial array of polarizing supermirrors)
2. Polarizer (Polarizing supermirrors)	6. Sample	10. Area detector (20×20 cm ²)
3. $\pi/2$ flipper (starts Larmor precession)	7. Second main solenoid (phase and correction coils)	
4. First main solenoid (phase and correction coils)	8. $\pi/2$ flipper (stops Larmor precession)	

Spin flippers

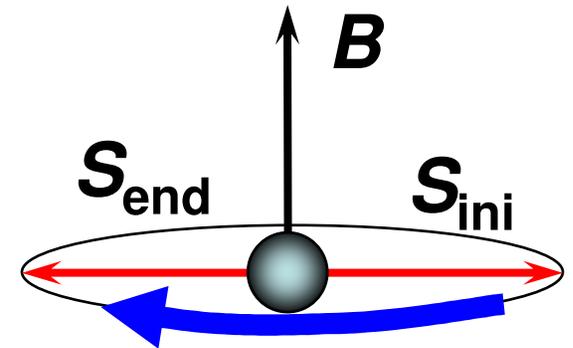
Precession



$\pi/2$ flipper



π flipper



Intensity at the detector

For a single wavelength:

$$\cos\left(2\pi\Delta N_0 \frac{\lambda}{\lambda_0}\right) \cos\left(2\pi N_0 \frac{\delta\lambda}{\lambda_0}\right)$$

For wavelength distribution, $f(\lambda)$, with mean wavelength, λ_0 :

$$\langle P \rangle = \int_0^\infty f(\lambda) \cos\left(2\pi\Delta N_0 \frac{\lambda}{\lambda_0}\right) \left[\int_{-\infty}^\infty S(\mathbf{Q}, \omega) \cos(\omega t(\lambda)) d\omega \right] d\lambda$$

where $t \equiv \frac{N_0 m \lambda^3}{h \lambda_0}$ since $\delta\lambda = \frac{m \lambda^3}{2\pi h} \omega$

$$\left[\int_{-\infty}^\infty S(\mathbf{Q}, \omega) \cos(\omega t(\lambda)) d\omega \right]$$

Intermediate Scattering Function $I(Q, t)$

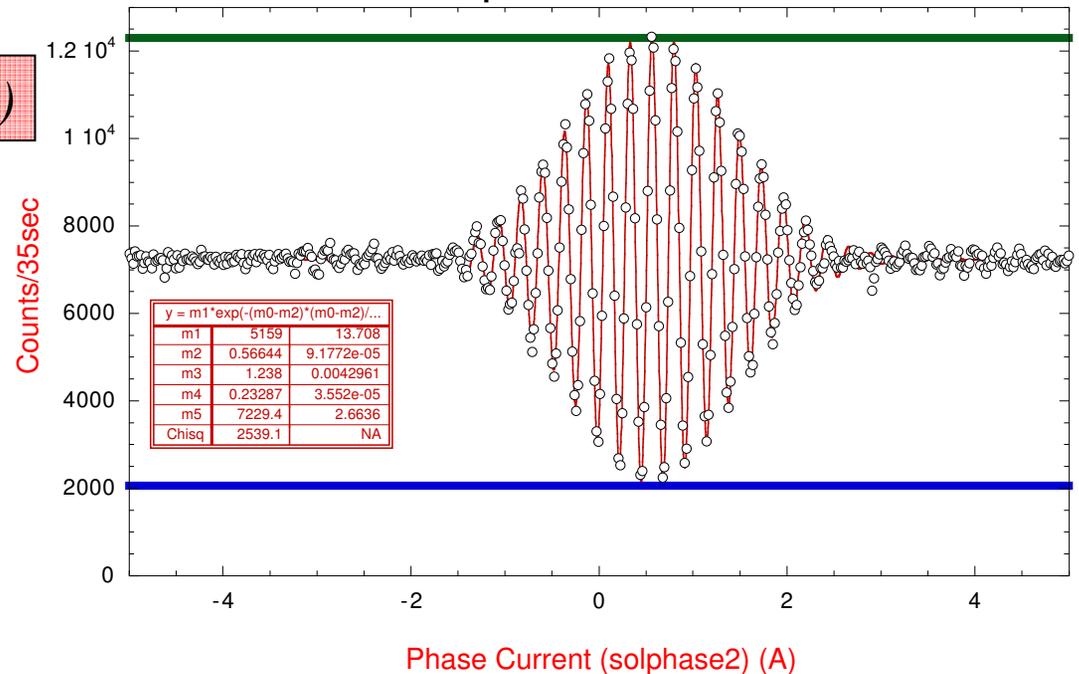
at $t = 0$

$$\langle P \rangle = \int_0^\infty f(\lambda) \cos\left(2\pi\Delta N_0 \frac{\lambda}{\lambda_0}\right) d\lambda$$

At small N_0 vary ΔN_0 :

- Period gives λ_0
- Envelope gives $f(\lambda)$

1nsec_8A_19990609.dat
1 cm apertures before solmain1 and after solmain2
solphase1 = 1.1296 A

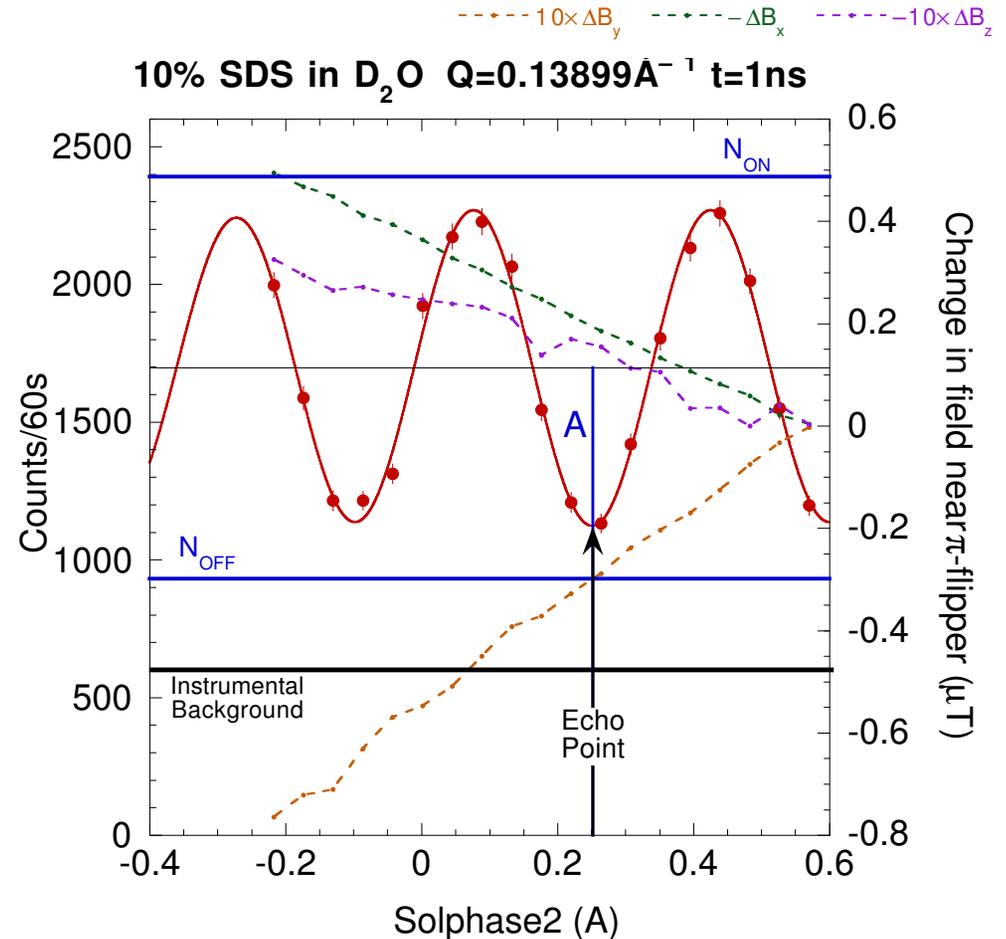


Measuring $I(Q,t)$

- The difference between the flipper ON and flipper OFF data gives $I(Q,0)$
- The echo is fit to a gaussian-damped cosine.

Signal before resolution correction is

$$\frac{2A}{N_{ON} - N_{OFF}}$$



How to deal with the resolution?

$$\langle P \rangle = \int_0^\infty f(\lambda) \cos\left(2\pi\Delta N_0 \frac{\lambda}{\lambda_0}\right) \left[\int_{-\infty}^\infty S(\mathbf{Q}, \omega) \cos(\omega t(\lambda)) d\omega \right] d\lambda$$

Inhomogeneities in the magnetic field may further reduce the polarization. Since they are not correlated with $S(\mathbf{Q}, \omega)$ or $f(\lambda)$, their effect may be divided out by measuring the polarization from a purely elastic scatterer.

$$\left[\int_{-\infty}^\infty S(\mathbf{Q}, \omega) \cos(\omega t(\lambda)) d\omega \right] = I(\mathbf{Q}, t(\lambda))$$

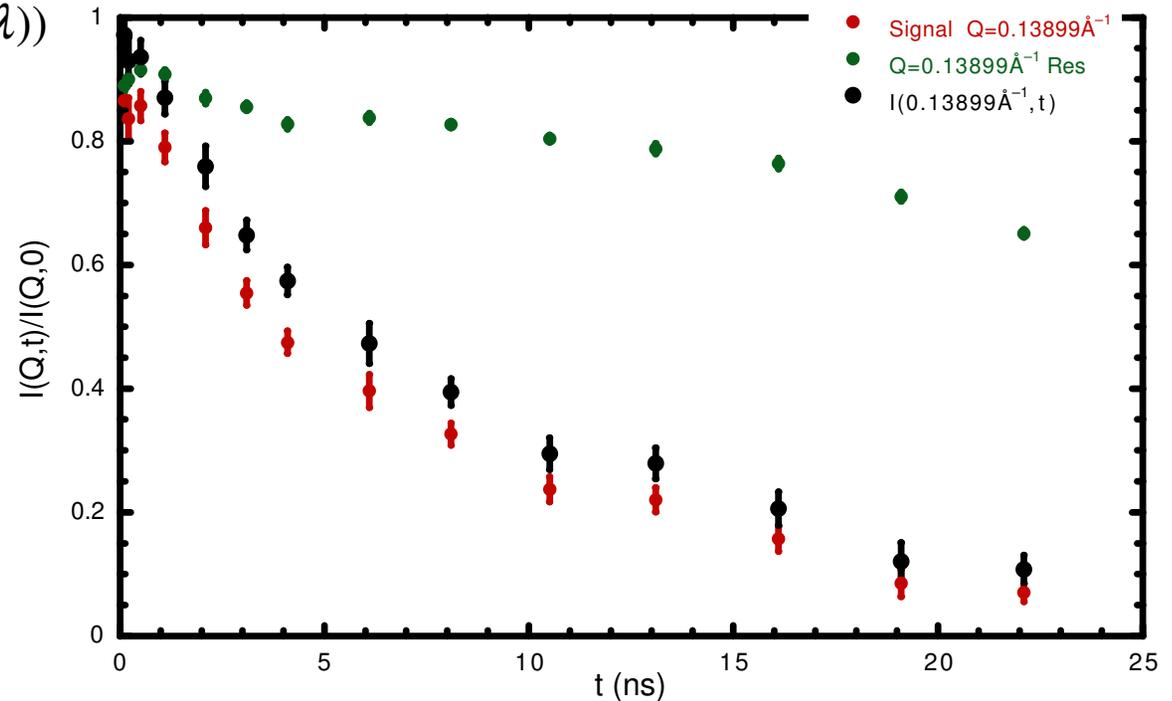
At the echo point, $\Delta N_0 = 0$,

$$\langle P \rangle = \int_0^\infty f(\lambda) I(\mathbf{Q}, t(\lambda)) d\lambda$$

$$J(\mathbf{Q}, t) = I(\mathbf{Q}, t) \cdot R(\mathbf{Q}, t)$$

$$I(\mathbf{Q}, t) = \frac{J(\mathbf{Q}, t)}{R(\mathbf{Q}, t)}$$

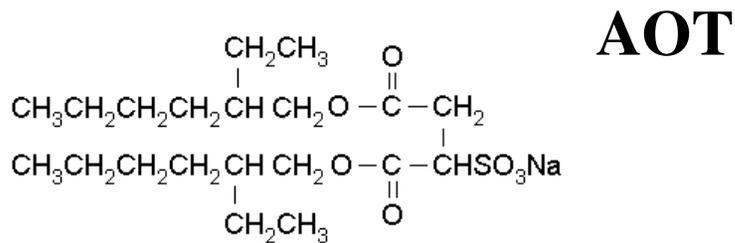
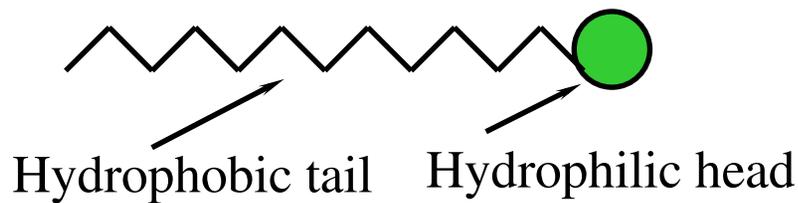
In the time domain the resolution is simply divided



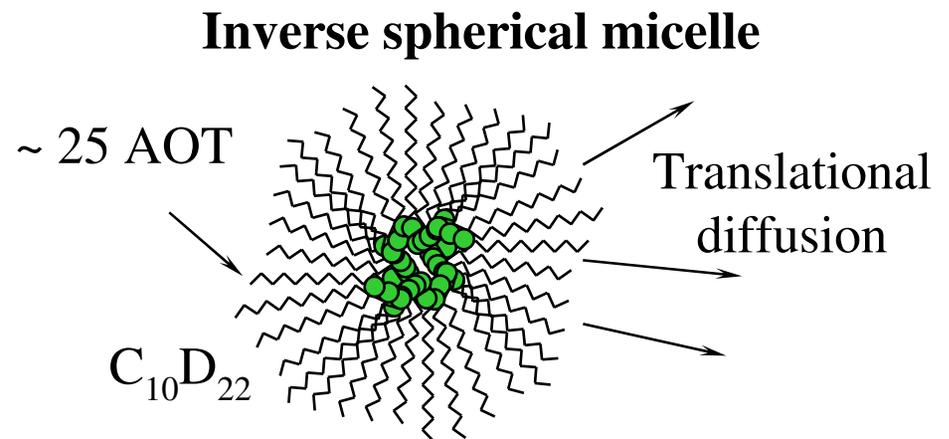
The main application of NSE is to measure the intermediate coherent scattering function $I_{coh}(Q,t)$, the coherent density fluctuations that correspond to some SANS intensity pattern.

- Diffusion
- Internal dynamics (shape fluctuations)
- ...

Example: Diffusion of Surfactant Molecules



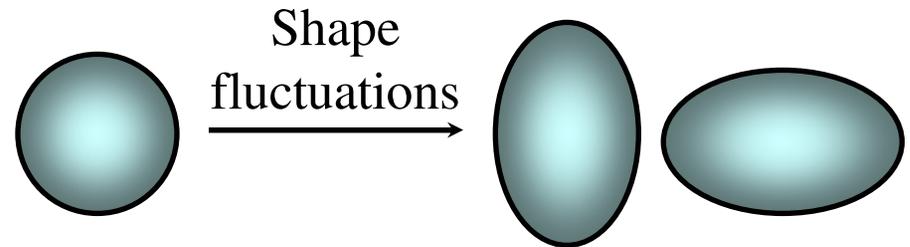
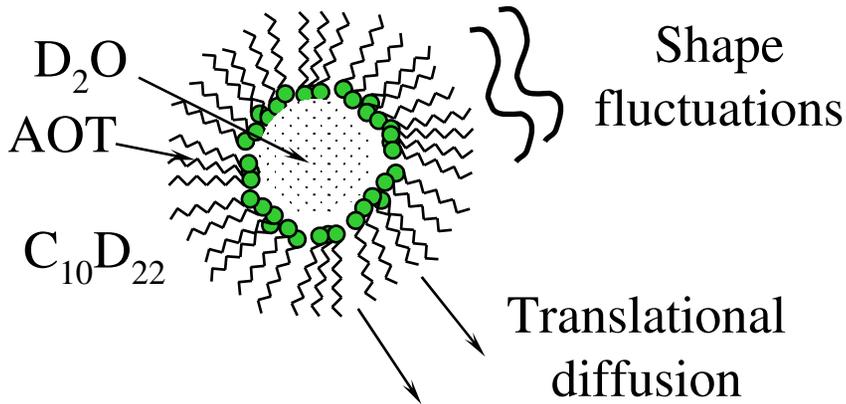
AOT micelles in n-decane ($\text{C}_{10}\text{D}_{22}$)



$$\frac{I(Q, t)}{I(Q, 0)} = \text{Exp} \left[- D_{eff} Q^2 t \right]$$

Experiment

Shape fluctuations in AOT/D₂O/C₆D₁₄ inverse microemulsion droplet

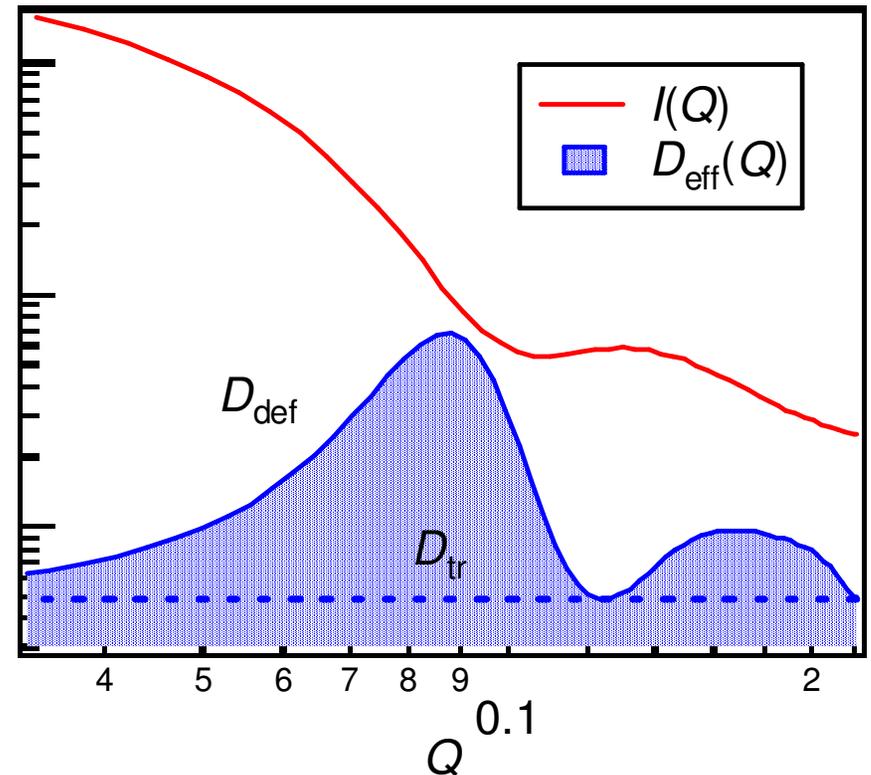


$$\frac{I(Q, t)}{I(Q, 0)} = \text{Exp}[-D_{\text{eff}}(Q)Q^2 t]$$

$$D_{\text{eff}}(Q) = D_{\text{tr}} + D_{\text{def}}(Q) =$$

$$D_{\text{tr}} + \frac{5\lambda_2 f_2(QR_0) \langle |a_2|^2 \rangle}{Q^2 [4\pi [j_0(QR_0)]^2 + 5f_2(QR_0) \langle |a_2|^2 \rangle]}$$

$$f_2(QR_0) = 5[4j_2(QR_0) + QR_0 j_3(QR_0)]$$



Experiment

$$D_{eff}(Q) = D_{tr} + \frac{5\lambda_2 f_2(QR_0) \langle |a_2|^2 \rangle}{Q^2 \left[4\pi [j_0(QR_0)]^2 + 5f_2(QR_0) \langle |a_2|^2 \rangle \right]}$$

Goal: Bending modulus of elasticity

$$k = \frac{1}{48} \left[\frac{k_B T}{\pi p^2} + \lambda_2 \eta R_0^3 \frac{23\eta' + 32\eta}{3\eta} \right]$$

λ_2 – the damping frequency – **frequency of deformation**

$\langle |a|^2 \rangle$ – mean square displacement of the 2-nd harmonic – **amplitude of deformation**

p^2 – size polydispersity, measurable by SANS or DLS

η is the bulk viscosity of deuterated n-hexane

η' is the bulk viscosity of deuterated water